

In the Specification:

Please replace paragraph [0050] with the following amended paragraph [0050].

[0050] In addition, more than one flexible member and associated supports may be used. Preferably, three flexible members such as the flexible member 310 shown in FIG. 3 are employed. Each flexible member is supported by a movable base such as movable base 312, support members 330, 332, and an actuator components 314, 316, and 318. Movement of the table in the z direction is achieved by moving the three movable bases in unison. Movement of the table in the  $\theta_x$  and  $\theta_y$  directions is achieved by moving the movable bases differentially.